# SECONDARY FLOWS AND FLUID INSTABILITY BEIWEEN ROTATING CYLINDERS 

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PMM Vol.30, N: 4, 3966. pp.688-698<br>V.I. JUOOVITH<br>(Rostov on-Don)<br>(Received January 25, 1966)

Experiments indicate that when Couette flow between rotating cylinders becomes unstable, a new steady flow arises. Mathematically this means that the corresponding steady-state boundary value problem for the Navier-Stokes equations has more than one solution. The purpose of the present study is to prove this fact in the case where the cylinders are rotating in the same direction. The indicated phenomenon occurs not only for Couette flow, but also for a certain class of fluid flows.

The method employed here is based on Krasnosel'ski1's theorem [1] on the bifurcation points of operator equations. The application of this theorem to Navier-Stokes equations was considered in [2], where the nonuniqueness of the solution of a certain steady-state spatially periodic problem was demonstrated.

The most difficult task involved in the application of Krasnosel'skif's theorem is the investigation of the spectra of innearized problems. In the case we are about to consider the study of the spectrum is facilitated by the results of Krein and Gantmakher on oscillatory integral operators [ 3 to 5].

The principal conclusions concerning bifurcation are formulated in Theorem 4.1 and in the notes made in connection with it.

We shall also show that the flows under consideration are unstable for large Reynolds numbers (see Theorem 5.1).

1. Formulation of the problem. Let any viscous incompressible homogeneous fluid fill the cavity between two coaxial cylinders with $r=r_{1}$ and $r=r_{2} ; r, \theta, z$ are cylindrical coordinates. We shall attempt to find the axisymmetrical steady-state flows, i.e. flows such that the velocity components $v_{r}^{\prime}, v_{\theta}^{\prime}, v_{z}^{\prime}$ depend solely on $r$ and $z$ and are independent of $\theta$. We shall also assume that $v_{r}{ }^{\prime}, v_{\theta}{ }^{\prime}, v_{z}{ }^{\prime}$ are periodic relative to $z$ with a period $2 \pi / \alpha_{0}$, and that the velocity flux through the transverse cross section of the cavity is 0

$$
\begin{equation*}
\int_{r_{1}}^{r_{2}} v_{z}^{\prime}(r, z) r d r=0 \tag{1.1}
\end{equation*}
$$

Assuming that the cylinders are solid and rotate with the angular velocities $\omega_{2}$ and $w_{2}$, respectively, and that the vector of the vortical mass forces $F$ is of the form ( $0, \nu F(r), 0$ ), it is easy to see that all of the requirements posed are satisfied by flow with a velocity vector $v_{o}$ and a pressure $P_{0}$

$$
\begin{equation*}
\binom{v_{0 r}=v_{0 z}=0}{v_{00}=v_{0}(r)}, \quad P_{0}=\int_{r_{1}}^{r} \frac{v_{0}^{2}(\rho)}{\rho} d \rho+\text { const } \tag{1.2}
\end{equation*}
$$

where the function $v_{0}(r)$ is defined unamblguously as the solution of the boundary value problem

$$
\begin{equation*}
\left(\frac{d^{2}}{d r^{2}}+\frac{1}{r} \frac{d}{a r}-\frac{1}{r^{2}}\right) v_{0}=-F(r) \quad\binom{v_{0}\left(r_{1}\right)=\omega_{1} r_{1}}{v_{0}\left(r_{2}\right)=\omega_{2} r_{2}} \tag{1.3}
\end{equation*}
$$

We further assume that $F$, and therefore $v_{0}$, do not depend on the coefficient of viscosity $v$. Specifically, if $F=0$, then (1.2) represents Couette flow,

$$
\begin{equation*}
v_{0}(r)=a r+\frac{b}{r}, \quad a=\frac{\omega_{2} 2_{2}^{2}-\omega_{1} r_{1}^{2}}{r_{2}^{2}-r_{1}^{2}}, \quad b=\frac{\left(\omega_{1}-\omega_{2}\right) r_{1}^{2} r_{2}^{2}}{r_{2}^{2}-r_{1}^{2}} \tag{1.4}
\end{equation*}
$$

Seeking solutions $v^{\prime}, P^{\prime}$ of the formulated problem which differ from (1.3) in the form

$$
\begin{equation*}
\mathbf{v}^{\prime}=\mathbf{v}+\mathbf{v}_{0}, \quad p^{\prime}=v p+p_{0} \tag{1.5}
\end{equation*}
$$

we obtain the following system of equations for determining $v, p$ :

$$
\begin{gather*}
\frac{1}{r} \frac{\partial}{\partial r}\left(r v_{r}\right)+\frac{\partial v_{z}}{\partial z}=0  \tag{1.6}\\
\Delta v_{r}-\frac{v_{r}}{r^{2}}-\frac{\partial p}{\partial r}=\lambda\left[v_{r} \frac{\partial v_{r}}{\partial r}+v_{z} \frac{\partial v_{r}}{\partial z}-1 \frac{v_{\theta}^{2}}{r}-2 \frac{v_{0}}{r} v_{\theta}\right] \\
\Delta v_{\theta}-\frac{v_{\theta}}{r^{2}}=\lambda\left[v_{r} \frac{\partial v_{\theta}}{\partial r}+v_{z} \frac{\partial v_{\theta}}{\partial z}+\frac{v_{r} v_{\theta}}{r}+\left(\frac{d v_{\theta}}{d r}+\frac{v_{0}}{r}\right) v_{r}\right] \\
\Delta v_{z}-\frac{\partial p}{\partial z}=\lambda\left[v_{r} \frac{\partial v_{z}}{\partial r}+v_{z} \frac{\partial v_{z}}{\partial z}\right] \quad\left(\lambda=\frac{1}{v}, \Delta=\frac{\partial^{2}}{\partial r^{2}}+\frac{1}{r} \frac{\partial}{\partial r}+\frac{\partial^{2}}{\partial z^{2}}\right)
\end{gather*}
$$

Here the functions $v_{r}, v_{\theta}, v_{z}$ must be $2 \pi / \alpha_{0}$-periodic relative to $z$ and vanish for $r=r_{1}, r_{2}$. The fulfillment of the condition

$$
\begin{equation*}
\int_{r_{1}}^{r_{z}} v_{z}(r, z) r d r=0 \tag{1.7}
\end{equation*}
$$

which follows from (1.1), is also required.
The linearized problem which corresponds to problem (1.6) to (1.7) is of the form

$$
\begin{gather*}
\frac{1}{r} \frac{\partial}{\partial r}\left(r u_{r}\right)+\frac{\partial u_{z}}{\partial z}=0, \quad \Delta u_{r}-\frac{u_{r}}{r^{2}}-\frac{\partial q}{\partial r}=-\lambda \frac{2 v_{0}}{r} u_{\theta}  \tag{1.8}\\
\Delta u_{\theta}-\frac{u_{\theta}}{r^{2}}=\lambda\left(\frac{d v_{0}}{\partial r}+\frac{v_{0}}{r}\right) u_{r}, \quad \Delta u_{z}-\frac{\partial q}{\partial z}=0, \quad \int_{r_{1}}^{r_{z}} u_{z} r d r=0
\end{gather*}
$$

and the conjugate problem is

$$
\begin{align*}
& \frac{1}{r} \frac{\partial}{\partial r}\left(r w_{r}\right)+\frac{\partial w_{z}}{\partial z}=0, \quad \Delta w_{r}-\frac{w_{r}}{r^{2}}-\frac{\partial Q}{\partial r}=\lambda\left(\frac{d v_{0}}{d r}+\frac{v_{0}}{r}\right) w_{\theta}  \tag{1.9}\\
& \Delta w_{\theta}-\frac{w_{\theta}}{r^{2}}=-\lambda 2 \frac{v_{0}}{r} w_{r}, \quad \Delta w_{z}-\frac{\partial Q}{\partial z}=0, \quad \int_{r_{3}}^{r_{2}} w_{z} r d r=0
\end{align*}
$$

The boundary conditions for the vectors $u, w$ are the same as, for the vector $v^{\prime}$.

Let us consider the set $N$ of doubly continuously differentiated solenoidal vectors $\left\{\nabla\right.$ \} which are defined in the closed domain $\left\{r_{1} \leq r \leq r_{2} ;-\infty<\right.$ $<z<+\infty)$, are axisymmetrical $\left(v_{r}, v_{\theta}, v_{z}\right.$ are independent of $\theta$ ), vanish for $r=r_{1}, r_{2}$ have a flux of zero through the transverse cross section of the cavity, and are such that $v_{1}, v_{\theta}$ are even functions of $z$, and $v_{z}$ is odd. By $H_{1}{ }^{\circ}$ we denote the Hilbert space obtained by supplementing the set $M$ with respect to the norm generated by the scalar product

$$
\begin{gathered}
(\mathbf{v}, \mathbf{u})_{H_{1} \bullet}=-\int_{-\pi / \alpha_{\theta}}^{\pi / \alpha_{0}} d z \int_{r_{1}}^{r} \Delta \mathbf{v u r d r}= \\
=-\int_{-\pi / \alpha_{0}}^{\pi / \alpha_{0}} d z \int_{r_{1}}^{r_{z}}\left[\left(\Delta v_{r}-\frac{v_{r}}{r^{2}}\right) u_{r}+\left(\Delta v_{\theta}-\frac{v_{\theta}}{r^{2}}\right) u_{\theta}+\Delta v_{z} u_{z}\right] r d r .
\end{gathered}
$$

Inverting the operator defined by relations (1.6) and (1.7) for $\lambda=0$, we reduce problem (1.6), (1.7) to the cperator equation

$$
\begin{equation*}
\mathbf{v}=\lambda K_{0} \mathbf{v} \tag{1.10}
\end{equation*}
$$

In a similar way, problems (1.8) and (1.9) are reducible to the operator equations

$$
\begin{equation*}
\mathbf{u}=\lambda A_{0} \mathbf{u}, \quad \mathbf{w}=\lambda A_{0}{ }^{*} \mathbf{w} \tag{1.11}
\end{equation*}
$$

- The operators $K_{0}, A_{0}, A_{0}{ }^{*}$ are completely continuous in the space $H_{1}{ }^{\circ}$; the operator $A_{0}$ is the Frechet differential of the operator $K_{0}$ at the point $v=0$; $A_{0}{ }^{*}$ is the adjoint of $A_{0}$ in $H_{1}{ }^{\circ}$. All of this follows from the results of [2]. We note that $H_{1}{ }^{\circ}$ is a subspace of the space $H_{1}$ considered in [2], and that the operators $K_{0}, A_{0}, A_{0}{ }^{*}$ are the contractions of the operators $K, A, A^{*}$ of [2] onto the (invariant) subspace $H_{1}{ }^{\circ}$.

2. Reduction to an integral equation. By expanding in a Fourier series we see that the solution of spectral problem (1.8) is a linear combination of solutions of the form

$$
\begin{array}{cc}
u_{r}=u(r) \cos \alpha z, & u_{\theta}=v(r) \cos \alpha z  \tag{2.1}\\
u_{z}=w(r) \sin \alpha z, & q=x(r) \cos \alpha z
\end{array}
$$

where $\alpha=k \alpha_{0}$ ( $k$ is a natural number) and the functions $w, x$ are expressed in terms of $u$ and $v$ by Formulas

$$
w(r)=-\frac{1}{\alpha r} \frac{d}{d r}(r u), \quad x(r)=-\frac{1}{\alpha}\left(\frac{d^{2}}{d r^{2}}+\frac{1}{r} \frac{d}{d r}-\alpha^{2}\right) w
$$

The functions $u, v$ and the corresponding eigenvalue of $\lambda$ are determined by solving the spectral problem

$$
\begin{aligned}
\left(L-\alpha^{2}\right)^{2} u & =2 \alpha^{2} \lambda \omega v,\left(L-\alpha^{2}\right) v=-\lambda g u, \quad u=v=u^{\prime}=0 \quad\left(\text { for } r \quad r_{1}, r_{2}\right) \\
\omega(r) & =\frac{v_{0}}{r}, \quad g(r)=-\left(\frac{d v_{0}}{d r}+\frac{v_{0}}{r}\right), \quad L=\frac{d^{2}}{d r^{2}}+\frac{1}{r} \frac{d}{d r}-\frac{1}{r^{2}} \quad(2.2)
\end{aligned}
$$

Naturally enough, the aforementioned linear combination contains onlv those solutions of (2.1) which have the same corresponding value of $\lambda$. The functions $w$ and $g$ will henceforth be considered continuous.

Now let us reduce problem (2.2) to an integral equation. Let $G_{1}(r, \rho)$, $G_{2}(r, p)$ be the Green's functions of the differential operators $-r\left(L-a^{2}\right)$, $r\left(L-\alpha^{2}\right)^{2}$ with the boundary conditions $u=0$ and $u=u^{\prime}=0\left(r=r_{1}, r_{2}\right)$, respectively. Let $G_{1}, G_{2}$ be integral operators given by Formulas

$$
\begin{equation*}
G_{k} f=\int_{r_{1}}^{r_{2}} G_{k}(r, \rho) f(\rho) \rho d \rho \tag{2.3}
\end{equation*}
$$

Both Green's functions $G_{1}(r, p)$ and $G_{2}(r, p)$ are continuous with respect to $r, \rho$ and symmetrical. As we know, this follows from the symmetry of the corresponding differential operators.

Let us denote by $H_{0}$ the Hilbert space $L_{2}$ with the weight $r$ on the segment $\left[r_{1}, r_{2}\right]$. The scalar product in $H_{0}$ is given by Formula

$$
\begin{equation*}
(\varphi, \psi)_{H_{0}}=\int_{r_{t}}^{r_{2}} \varphi(r) \psi(r) r d r \tag{2.4}
\end{equation*}
$$

The operators $G_{1}, G_{2}$ defined by. Formula (2.3) are symmetrical and completely continuous in $H_{0}$.

Problem (2.2) is equivalent to finding the spectrum of the system of integral equations

$$
\begin{equation*}
u=2 \alpha^{2} \lambda G_{2} \omega v, \quad v=\lambda G_{1} g u \tag{2.5}
\end{equation*}
$$

or any of the integral equations

$$
\begin{equation*}
u=\mu G_{2} \omega G_{1} g u, \quad v=\mu G_{1} g G_{2} \omega v \quad\left(\mu=2 x^{2} \lambda^{2}\right) \tag{2.6}
\end{equation*}
$$

Here $\omega, g$ denote the operators of multiplication by the functions $w(r)$ and $g(r)$, respectively.

Similarly, seeking the solution of conjugate problem (1.9) in the form $w_{r}=u_{1}(r) \cos \alpha z, w_{\theta}=v_{1}(r) \cos \alpha z, w_{z}=w_{1}(r) \sin \alpha z, Q=x_{1}(r) \cos \alpha z$

$$
\begin{equation*}
\left(w_{1}(r)=-\frac{1}{\alpha r} \frac{d}{d r}\left(r u_{1}\right)_{r} \quad x_{1}(r)=-\frac{1}{\alpha}\left(\frac{d^{2}}{d r^{2}}+\frac{1}{r} \frac{d}{d r}-\alpha^{2}\right) w_{1}\right) \tag{2.7}
\end{equation*}
$$

we arrive at the problem of eigenvalues for determining $u_{1}, v_{1}$

$$
\begin{gather*}
\left(L-\alpha^{2}\right)^{2} u_{1}=\lambda \alpha^{2} g v_{1}, \quad\left(L-\alpha^{2}\right) v_{1}=-2 \lambda_{\omega} u_{1} \\
u_{1}=u_{1}^{\prime}=v_{1}=0 \quad\left(\text { for } \quad r=r_{1}, r_{2}\right) \tag{2.8}
\end{gather*}
$$

Problem 2.8 is equivalent to the system of integral equations

$$
\begin{equation*}
u_{1}=\lambda \alpha^{2} G_{2} g v_{1}, \quad v_{1}=2 \lambda G_{1} \omega u_{1} \tag{2.9}
\end{equation*}
$$

or to any of the integral equations

$$
\begin{equation*}
u_{1}=\mu G_{2} g G_{1} \omega u_{1}, \quad v_{1}=\mu G_{1} \omega G_{2} g v_{1} \tag{2.10}
\end{equation*}
$$

For specificity we shall next consider the first equation of (2.6), which can be written as

$$
\begin{equation*}
u=\mu B u \quad\left(B=G_{2} \omega G_{1} g\right) \tag{2.11}
\end{equation*}
$$

Let $\mu>0$ be one of its eigenvalues. Then $\lambda= \pm \sqrt{\mu / 2 \alpha^{2}}$ is the eigenvalue of problem (2.2); $v$ can be found from the second formula of (2.5). The equation conjugate to (2.11) is of the form

$$
\begin{equation*}
u_{0}=\mu B^{*} u_{0} \quad\left(B^{*}=g G_{1} \omega G_{2}\right) \tag{2.12}
\end{equation*}
$$

Combining the second equations of (2.10) and (2.12) we note that $u_{0}=g v_{1}$ is the solution of Equation (2.12).

Let us suppose that $\mu>0$ is a single eigenvalue of the operator $B$. Hence 1t follows (see [2], Lemma 1.5) that $\left(u, u_{0}\right)_{H_{0}}=\left(u, g v_{1}\right)_{H_{0}} \neq 0$.

Lemma 1.1 . Let $\mu>0$ be an eigenvalue of the operator $B=G_{2} G_{1} \theta$, and let its rank be 1 . Then $\lambda=\mp \sqrt{\mu / 2 \alpha^{2}}$ is an eigenvalue of the operator $A_{0}(\operatorname{see}(1.22))$, and its rank is also 1 .

Proof. Let us compute the scalar producy (u, $w) H_{1}{ }^{\circ}$, where $u, W$ are the eigenvectors of the operators $A_{0}, A_{0}{ }^{*}$ defined by Equations (2.1) and (2.7) which correspond to the eigenvalue $\lambda$. Multiplying the second third and fourth equations of (1.8) by $w_{r}, w_{9}$ and $w_{z}$ respectively, we find that

$$
\begin{equation*}
(\mathbf{u}, \mathbf{w})_{H_{1}}=\lambda \int_{-\pi / \alpha_{\theta}}^{\pi / \alpha_{0}} \int_{r_{1}}^{r_{z}}\left(2 \omega u_{\theta} w_{r}+g u_{r} w_{\theta}\right) r d r d z \tag{2.13}
\end{equation*}
$$

With the aid of (2.1) and (2.7) the second equation and the first equation of (2.9), we find from (2.13) that

$$
\begin{aligned}
(\vec{u}, \bar{w})_{H_{1}{ }^{\circ}}= & \frac{\pi \lambda}{\alpha_{0}} \int_{r_{1}}^{r_{2}}\left(2 \omega v u_{1}+g u v_{1}\right) r d r=\frac{\pi \lambda}{\alpha_{0}}\left[\left(\mu \omega G_{1} g u, G_{2} g v_{1}\right\rangle_{H_{0}}+\left(u, u_{0}\right)_{H_{0}}\right]= \\
& =\frac{\pi \lambda}{\alpha_{0}}\left[\left(\mu G_{2} \omega G_{1} g u, g v_{1}\right)_{H_{0}}+\left(u, u_{0}\right)_{H_{0}}\right]=\frac{2 \pi \lambda}{\alpha_{0}}\left(u, u_{0}\right)_{H_{0}} \neq 0
\end{aligned}
$$

Hence it follows that the rank of the eigenvalue $\lambda$ is unity. Lemma has been proved.
3. On Green's funotions $a_{1}$ and $\sigma_{2}$. Let us consider the aifferential operators $-r\left(L-\alpha^{2}\right), r\left(L-\alpha^{2}\right)^{2}$, which can be represented in the form

$$
\begin{array}{ll}
-r\left(L-\alpha^{2}\right) u=\rho_{0} \frac{d}{d r} \rho_{1} \frac{d}{d r} \rho_{2} u  \tag{3.1}\\
r\left(L-\alpha^{2}\right)^{2} u=\rho_{0} \frac{d}{d r} \rho_{1} \frac{d}{d r} \rho_{2} \rho_{0} \frac{d}{d r} \rho_{1} \frac{d}{d r} \rho_{2} u & \binom{\rho_{0}(r)=\rho_{2}(r)=I_{1}(\alpha r)}{\rho_{1}(r)=r / \rho_{2}^{2}}
\end{array}
$$

Here $\rho_{0}(r), \rho_{1}(r), \rho_{2}(r)$ are positive functions and $I_{1}$ is a modified Bessel function.

In accordance with results of Krein [3] this implies that $G_{1}(r, \rho)$, $G_{2}(r, \rho)$ are oscillatory kernels. This means that the following conditions are fulfilled:

$$
\text { 1. } G_{k}(r, \rho)>0 \quad\left(r_{1}<r, \rho<r_{2}\right)
$$

```
2. \(\quad \operatorname{det}\left\|G_{k}\left(\eta_{i}, \rho_{s}\right)\right\|_{i, s=1}^{n} \geqslant 0 \quad\) for \(\quad r_{1}<\rho_{\rho_{1}}<\rho_{2}<\ldots<\rho_{n}<\eta_{2}<\eta_{2}\)
3. \(\operatorname{det}\left\|G_{k}\left(\rho_{i}, \rho_{s}\right)\right\|_{i, s=1}^{n}>0 \quad\) for \(r_{1}<p_{1}<\ldots<\rho_{n}<r_{2}\)
```

An integral operator with an oscillatory kernel will be called oscillatory; $G_{1}$ and $G_{2}$ are oscillatory operators.

Further on we shall require the following Lemma.
Lemma 2.1. The operators $G_{1}$ and $G_{z}$ in the strip $|\operatorname{Im} \alpha|<\delta_{0}$ are analytic functions of the parameter $\alpha$, i.e. in the neighborhood of any a from this strip they can be expanded in Taylor series which converge in the norm of operators. The positive number $\delta_{0}$ depends solely on $r_{2}$ and $r_{2}$.
$\mathrm{Pr} \circ \circ \mathrm{f}$. Let us make use of the familiar fact (e.g. see [8]) that if a linear operator depends analytically on a parameter within some range of its variation and has an inverse operator, then the inverse operator is an analytic function of the parameter in the same range.

The boundary value problems

$$
\begin{align*}
& \left(L-\alpha^{2}\right) v=-f, \quad v=0 \quad \text { for } \quad r=r_{1}, r_{2} \\
& \left(L-\alpha^{2}\right)^{2} u=f, \quad u=u^{\prime}=0 \quad \text { for } \quad r=r_{1}^{\prime}, r_{2} \tag{3.2}
\end{align*}
$$

are equivalent, respectively, to the integral equations

$$
\begin{equation*}
v+\alpha^{2} G_{10} v=G_{10} f, \quad u-2 \alpha^{2} G_{20} L u+\alpha^{4} G_{20} u=G_{20} f \tag{3.3}
\end{equation*}
$$

where $G_{\mathrm{k}}$ ( $k=1,2$ ) means the operator $G_{k}$ for $\alpha=0$.
From (3.3) we have the following representations of the operators $G_{1}, G_{2}$ :

$$
\begin{equation*}
G_{1}=\left(I+\alpha^{2} G_{10}\right)^{-1} G_{10}, \quad G_{2}=\left(I-2 \alpha^{2} G_{20} L+\alpha^{4} G_{20}\right)^{-1} G_{20} \tag{3,4}
\end{equation*}
$$

We note that the operators $G_{10}, G_{20}$ are completely continuous, symmetrical and positive, and that the operator $G_{20} L$ admits of extension to a completely continuous operator (integration by parts transforms it into an integral operator with a continuous kernel).

It is now sufficient to establish that operators inverse to those of (3.4) exist for any $\alpha$ from some strip $|\operatorname{Im} a|<\delta_{0}$. Let the eigenvalues of the operator $G_{1}$ be $0<\delta_{1}{ }^{2} \leq \delta_{2}{ }^{2}<\ldots<\delta_{n}{ }^{2}<\ldots$, and let $\delta_{n}{ }^{2} \rightarrow \infty$ as $n \rightarrow \infty$. Then the operator $\left(I+\alpha^{3} G_{10}\right)^{-1}$ exists for any $\alpha$ except $\alpha=\mp i \delta_{1}, \mp i \delta_{2}, \ldots$ and, in any case, for any $\alpha$ from the strip $|\operatorname{Im} \alpha|<\delta_{1}$. This proves the required statement about the operator $G_{1}$

We shall now ohow that if the quantity $\mid$ Im $\alpha \mid$ is sufficiently small, then the second equation of (3.3) for $f=0$, or (equivalently), the second boundary value problem of (3.2) for $f=0$ has a zero solution only. Multiplying the second equation of (3.2) for $f=0$ by $u^{*}$ and integrating over $r$ from $r_{1}$ to $r_{2}$ we obtain

$$
\begin{equation*}
\|u\|_{2}^{2}+2 a^{2}\|u\|_{1}^{2}+\alpha^{4}\|u\|_{0}^{2}=0 \tag{3.5}
\end{equation*}
$$

$$
\left(\|u\|_{0}=\|u\|_{H_{0}},\|u\|_{2}=\|L u\|_{H_{0}},\|u\|_{1}{ }^{2}=\int_{r_{1}}^{r_{2}}\left|\frac{d u}{d r}+\frac{u}{r}\right|^{2} r d r\right)
$$

Setting $\alpha=y+t \delta$ and separating the real and imaginary parts in (3.5), we obtain

$$
\begin{gather*}
\|u\|_{2}^{2}+2\left(\gamma^{2}-\delta^{2}\right)\|u\|_{1}^{2}+\left[\left(\gamma^{2}-\delta^{2}\right)^{2}-4 \gamma^{2} \delta \delta^{2}\right]\|u\|_{0}^{2}=0  \tag{3.6}\\
\gamma \delta\left[\|u\|_{2}^{2}+\left(\gamma^{2}-\delta^{2}\right)\|u\|_{0}^{2}\right]=0 \tag{3.7}
\end{gather*}
$$

As we know (see [7]), the following inequalities are valid:

$$
\begin{equation*}
\|u\|_{6} \leqslant c_{0}\|u\|_{1}, \quad\|u\|_{1} \leqslant c_{1}\|u\|_{2} \tag{3.8}
\end{equation*}
$$

$\begin{aligned} & \text { Where } \\ & \text { set }\end{aligned} a_{0}, c_{1}$ are positive constants which depend only on $r_{1}$ and $r_{z}$. We

$$
\delta_{0}=\min \left\{\delta_{1}, \frac{1}{c_{0}}, \frac{1}{c_{1} \sqrt{2}}\right\}
$$

and let $|\operatorname{Im} \alpha|=|\delta|<\delta_{0}$. Then the fact that $u=0$ follows: (1) for $\delta=0$ from (3.6), (2) for $\delta \neq 0, \gamma \neq 0$ from (3.7). In fact, from (3.7) and (3.8) we deduce that

$$
0=\|u\|_{1}{ }^{2}+\left(\gamma^{2}-\delta^{2}\right)\|u\|_{0}{ }^{2} \geqslant\left(1-\delta_{0}^{2} c_{0}^{2}\right)\|u\|_{L^{2}}+\gamma^{2}\|u\|_{0}^{2} \geqslant \gamma^{2}\|u\| 0_{0}^{2}
$$

3) for $\delta \neq 0,, y=0$ from (3.6). From (3.6),(3.8) for $y=0$ we find, in fact, that

$$
0=\|u\|_{a^{2}}^{2}-2 \delta^{2}\|u\|_{2}^{2}+\delta^{4}\|u\|_{0}^{2} \geqslant\left(1-2 \delta_{0}^{2} c_{1}^{2}\right)\|u\|_{2}^{2}+\delta^{4}\|u\|_{0}^{2} \geqslant \delta^{4}\|u\|_{0}^{2}
$$

The foregoing, in accordance with Fredholm's theorem, implies that for $|\operatorname{Im} \alpha|<\delta_{0}$ the operator $I-2 \alpha^{2} G_{20} L+\alpha^{4} G_{20}$ is invertible. The second expression of (3.4) implies that the operator $G_{2}$ in the strip $|\operatorname{Im} a|<\delta_{0}$ depends analytically on $a$. The Lemma has been proved.
4. The apeotrum of bifuraation. In the present section we shall establish conditions under which the operator $A_{0}$ defined in (1.11) has a real and singular spectrum. Prom this, by virtue of Krasnosel'skil's theorem, we deduce that each eigenvalue of the operator $A_{0}$ is a bifurcation point of the operator $K_{0}$ : for values of the parameter $\lambda$ which are close to it, Equation (1.10) and thereby boundary value problem (1.6),(1.7), have zero solutions.

Theorem 4.1. Let the conditions

$$
g\left(\dot{)^{2}}=-\left(d v_{0} / d r+v_{0} / r\right)>0 \quad \begin{array}{c}
\left.\omega(r)-v_{1}(r) / r>r<r_{2}\right) \\
\left(r_{1}<r<r_{2}\right) \tag{4.2}
\end{array}\right.
$$

be fulfilled
Then for any $\alpha_{0}$ with the exception of some denumerable set the operator $A_{0}$ has a sequence of positive and simple eigenvalues $0<\lambda_{1}<\lambda_{2}<\ldots$ each of which is a bifurcation point of Equation (1.10). All of the intervals $\left(\lambda_{1}, \lambda_{2}\right),\left(\lambda_{3}, \lambda_{4}\right) \ldots$ belong to the spectrum of Equation (1.10).

If condition (4.1) is fulfilled, and if the inequality

$$
\begin{equation*}
g(r)=-\left(d v_{0} / d r+v_{0} / r\right)<0 \tag{4.3}
\end{equation*}
$$

which is the opposite of (4.2) is satisfied instead of the latter, then the operator $A_{0}$ does not have any real eigenvalues, and there is no bifurcation.

Proof. Let conditions (4.1) and (4.2) be fulfilled. Since the product of the oscillatory operators is yet another oscillatory operator [ 3 to 5], the operator $R$ derined in (2.11) is oscillatory. According to the results of $[4$ and 5] this implies that its spectrum consists of a sequence of singular positive eigenvalues $0<\mu_{1}(\alpha)<\mu_{2}(\alpha)<\ldots<\mu_{n}(\alpha)<\ldots$ The spectrum of the operator $A_{0}$ therefore consists of the real eigenvalues

$$
\lambda_{i k}=\left(\frac{\mu_{i}\left(k \alpha_{0}\right)}{2 k^{2} \alpha_{0}^{2}}\right)^{1 / 2}, \quad \lambda_{i k}^{\prime}=-\left(\frac{\mu_{i}\left(k \alpha_{0}\right)}{2 k^{2} \alpha_{0}^{2}}\right)^{1 / 2} \quad(i, k=1,2, \ldots)
$$

According to Lenma 1.1, all of them have a rank of 1 . For this reascn the multiplicity of each of them is equal to the dimensionality of the free vector space. Thus, the multiplicity of an eigenvalue, let us say $\lambda_{i, k}$, is equal to the number of elements in the matrix. ( $\lambda_{1 k}$ ) situated in the same row and equal to $\lambda_{i, k} k_{1}$ (because of the singularity of eigenvalues $\mu_{1}$, the columns of the matrix ( $\lambda_{1 k}$ ) do not contain identical elements).

What follows is based on the following Lemma, which is a simple corollary of the theory of perturbations of the spectrum of a innear operator.

Lemma 4.1 . Let the linear operator $B(\alpha)$ be completely continuous and analytic with respect to $\alpha$ along the real axis. Let its spectrum consist of a sequence of positive and single eigenvalues $0<\mu_{1}(\alpha) \leqslant \mu_{2}(\alpha)<\ldots$ $\ldots<\mu_{\mathrm{i}}(\alpha)<\ldots$ Then all $\mu_{k}(\alpha)(k=1,2, \ldots)$ are analytic functions on the real axis.

Proof. According to perturbation theory (e.g. see [6 to 8]), the singularity of the eigenvalue $\mu_{k}(a)$ implies the possibility of its analytic extension along $\alpha$. In this case $\mu_{k-1}(\alpha)<\mu_{k}(\alpha)<\mu_{k+h}(\alpha) \quad(k=2,3, \ldots)$, is valid for any $\alpha$, since it cannot de violated without the appearance of a multiple eigenvalue for some value of $\alpha$. The Lemma has been proved.

It is sufficient to consider the eigenvalues $\lambda_{1 k}$.
Let us set $\Lambda_{i}(\alpha)=\sqrt{\mu_{i}(\alpha) / \alpha^{2}}$. (The function $\Lambda_{1}(\alpha)$ is analytic with respect to $\alpha$ on the positive semiaxis $\alpha>0$. We have $\lambda_{i k}=\Lambda_{i}\left(k \alpha_{0}\right)$. The set $\Gamma$ ff those $\alpha_{0}$ for which there are at least two identical numbers among the $\lambda_{1 k}$ is clearly the join over all natural $t, k, r, s$ of the sets $\Gamma_{1 k r}$, of those $\alpha_{0}$ for which the equation

$$
\begin{equation*}
\Lambda_{i}\left(k \alpha_{0}\right)-\Lambda_{r}\left(s a_{0}\right)=0 \tag{4.4}
\end{equation*}
$$

is fulfilled.
We shall show that the analytic function $\Lambda_{i k r s}(\alpha)=\Lambda_{i}(k \alpha)-\Lambda_{r}(s a)$ cannot be an identical zero.

In fact, setting for example $t>r$ and taking account of the inequality $\Lambda_{1}(\alpha)>\Lambda_{r}(\alpha)$, from the assumption that $\Lambda_{i k r s} \equiv 0$ we arrive at the conclusion

$$
\Lambda_{r}(s \alpha)=\Lambda_{i}(k \alpha)>\Lambda_{r}(k \alpha)
$$

which is impossible for $s=k$. If, on the other hand, $s \neq k$, then for any $0<\alpha<\infty$ and any natural $p$ we have

$$
\Lambda_{r}(\alpha)>\Lambda_{r}\left(\left(\frac{k}{s}\right)^{p} \alpha\right) \rightarrow+\infty \quad \text { for } \quad p \rightarrow \infty
$$

since $\Lambda_{r}(\alpha) \rightarrow \infty$ as $\alpha-0$ or $\infty$ (see Note 2 below). The same reasoning applies to the case $t=r$.

Now we can say that $\Gamma_{1 \times r i}$ as the set of zeros of the analytic function $\Lambda_{i k r}$ is not more than denumerable. Hence the set $\Gamma$ is not more than denumerable.
$\Gamma_{1 \mathrm{kr}}$ is, in fact, denumerable; 1 ts limiting points are 0 and $\infty$ (see Note 3 below).

Let $\alpha_{n} \bar{E}$. We number the eigenyalues $\lambda_{1 k}$ in increasing order to obtain the sequence of single eigenvalues of the operator $A_{0}: 0<\lambda_{1}<\lambda_{2}<\ldots$. Each of them, in accordance with Krasnosel'skil's theorem [1], is a bifurcation point of Equation (1.10).

From the results of [9] it follows that the rotation of the vector field $\left(I-\lambda K_{0}\right) v$ on spheres of large radius in the space $H^{\circ}$ is equal to +1 . For this reason, just as in [2] we find that equation (1.10) has nontrivial solutions for any $\lambda$ from the intervals $\left(\lambda_{1}, \lambda_{2}\right),\left(\lambda_{3}, \lambda_{4}\right) \ldots$ These intervals belong to the spectrum of the operator $K_{0}$.

If conditions (4.1) and (4.3) are fulfilled, then the operator $-B$ is oscillatory Hence, the operator $A 0$ has no real eigenvalues under these conditions (they are all imaginary), and there is no bifurcation. The theorem
has been proved.
$N \circ \operatorname{te} \quad 1$. The theorem and its proof remain valid if equality in individual points of the segment $\left(r_{1}, r_{2}\right)$ is admitted in (4.1) and (4.2). We can also consider very irregular $\omega$ and $\sigma$, e.g. replacing ardr by $d \sigma$ in the second integral operator of (2.10); here $\sigma$ is an arbitrary increasing function.
$\mathrm{N} \circ \mathrm{t} \mathrm{e} 2$. Let us call the quantity

$$
\Lambda_{0}=\min \Lambda_{1}(\alpha) \quad \text { for } 0<x<\infty
$$

he bifurcational critical Reynolds number.
We shall prove that $\Lambda_{0}>0$ and is attained for some value of $\alpha$.
Since the function $\Lambda_{1}(\alpha)$ is continuous for $\alpha \in(0, \infty)$, it is sufficient to establish that $\Lambda_{1}(\alpha) \rightarrow+\infty$ for $\alpha \rightarrow 0, \infty$. Since $\Lambda_{1}(\alpha)=\alpha^{-1} \sqrt{\mu_{1}(\alpha)}$, and $\mu_{1}(\alpha)$ is an analytic function on the entire real axis, and $\mu_{1}(0)>0$, it follows that

$$
\Lambda_{1}(\alpha) \sim \alpha^{-1} \sqrt{\mu_{1}(0)} \rightarrow+\infty \quad \text { for } \quad \alpha \rightarrow 0
$$

Further, multiplying the first two equations of (2.2) for $\lambda=\Lambda_{1}(a)$ by ru, - rv, respectively, and integrating over $\left[r_{1}, r_{2}\right]$, we obtain the relations (for notation see (3.5))
$\|u\|_{2}^{2}+2 \alpha^{2}\|u\|_{1}^{2}+\alpha^{4}\|u\|_{0}^{2}=2 \alpha^{2} \Lambda_{1} \int_{r_{1}}^{r_{2}} \omega v u r d r, \quad\|v\|_{1}^{2}+\alpha^{2}\|v\|_{0}^{2}=\Lambda_{1} \int_{r_{1}}^{r_{2}} g u v r d r$
We set

$$
\left.C=\max \operatorname{minax}_{r_{1} \leqslant r \leqslant r_{2}}|\omega(r)|, \quad \max |g(r)|\right\}
$$

Applying the Buniakowski inequality, we find from (4.5) that

$$
\begin{equation*}
\alpha^{n}\|u\|_{0}^{2} \leqslant 2 \Lambda_{1} C\|u\|_{0}\|v\|_{0}, \quad a^{2}\|v\|_{0}^{2} \leqslant \Lambda_{1} C\|u\|_{0}\|v\|_{0} \tag{4,6}
\end{equation*}
$$

By virtue of the fact that $(u, v)$ is a nonzero solution, we obtain from (4.6) the estimate

$$
\Lambda_{1} \geqslant \sqrt{2} \alpha^{2} / C \rightarrow+\infty \quad \text { for } \quad \alpha \rightarrow+\infty
$$

This proves our statement.
It remains uncertain whether it is true that flow (1.2) is stable for $\lambda<\Lambda_{0}$ ("principle of alteration of stability").

Note 3 . The exclusive denumerable set $\Gamma$ mentioned in the proof of the theorem actually does exist.

In fact, since the function $\lambda=\Lambda_{1}(\alpha) \rightarrow \infty$ as $\alpha \rightarrow 0$, $\infty$, we can point out two continuous branches of the inverse function $\alpha_{1}(\lambda), \alpha_{2}(\lambda)$ such that $\alpha_{1}(\lambda) \overrightarrow{0} ; \alpha_{2}(\lambda) \rightarrow \infty$ as $\lambda \rightarrow+\infty$. Then $a_{a}(\lambda) / \alpha_{1}(\lambda) \rightarrow+\infty$ as $\lambda \rightarrow \infty$, so that for each natural $k$ starting with some particular $k$ there exists an $\eta_{k}$ such that $\alpha_{2}\left(\eta_{k}\right)=k \alpha_{1}\left(\eta_{k}\right)$. Let us set $\alpha_{1}\left(\eta_{k}\right)=\alpha_{0}$. Then $\Lambda_{1}\left(k \alpha_{0}\right)=\Lambda_{1}\left(\alpha_{o_{k}}\right)$. the set $\Gamma_{k}$ contains all of the points $\alpha_{0_{k}}(k=1$, $2, \ldots$ ) and is therefore denumerable.

Approximate computations indicate (it would be interesting to have a rigorous proof of this) that $\Lambda_{1}(\alpha)$ is a downward convex function. If this is indeed the case, it follows that $\Lambda_{0}$ is attained for a unique value of ao , and that $\lambda_{1}\left(\alpha_{0}\right)$ is a bifurcation point in a certain one of its neighborhoods.

Note 4 . The theory of oscillatory operators [3 and 5] implies several things about the properties of the eigensolutions of problems (2.2).

For example, for solutions ( $u, v)$, $\left(u_{1}, v_{1}\right)$ of these problems which
correspond to the minimum eigenvalue, all of the functions $u, v, u_{1}, v_{1}$ retain the same sign on the segment $\left(r_{1}, r_{2}\right)$, while for the $k t h$ (in magnitude) eigenvalue, each of these functions changes sign $k-1$ times. The eigenvalues of each of the equations (2.6), (2.9) from a complete system in $H_{0}$.

Note 5. As an example, let us consider Couette flow (1.4). Here we have

$$
\begin{equation*}
\omega(r)=a+b / r^{2}, g(r)=-2 a \tag{4.7}
\end{equation*}
$$

From Theorem 4.1 we find that if the cylinders are rotating in the same direction, $\omega_{1}>0, \omega_{2} \geq 0$ (the outer cylinder can be at rest), then secondary steady flows arise with a certain Reynolds number, provided the condition

$$
\begin{equation*}
\omega_{2} r_{2}^{2}-\omega_{1} r_{1}^{2}<0 \tag{4.8}
\end{equation*}
$$

On the other hand, if the opposite inequality

$$
\begin{equation*}
\omega_{2} r_{2}^{2}-\omega_{1} r_{1}^{2}>0 \tag{4.9}
\end{equation*}
$$

applies, then there is no bifurcation. As we know (see [10 and 11]) in this case the Couette flow is stable relative to axisymmetrical perturbations for any Reynolds number.

Let us cite a simple proof of this fact (*).
We shall consider the nonsteadystate equations corresponding to system (1.8). These are obtained by adding the terms $-\lambda\left(\partial u_{r} / \partial t\right),-\lambda\left(\partial u_{0} / \partial t\right)$, $-\lambda\left(\partial u_{z} / \partial t\right)$ to the left-hand sides of the second, third, and fourth equations öf (1.8), respectively. Muitipiying these equations by $u_{r},-2 \omega / g\left(u_{\theta}\right)$, $u_{z}$, summing the resulting equations, and integrating over the domain $D\left(r_{1}<r<r_{2} ;|z|<\pi / a_{0}\right)$, we obtain

$$
\begin{gather*}
\frac{1}{2} \frac{d}{d t} \int_{D}\left(u_{r}^{2}+h u_{\theta}^{2}+u_{z}^{2}\right) r d r d z=-v \int_{D}\left[\left(\frac{\partial u_{r}}{\partial r}\right)^{2}+\left(\frac{\partial u_{r}}{\partial z}\right)^{2}+\frac{u_{r}^{2}}{r^{2}}+\right. \\
\left.+\left(\frac{\partial u_{z}}{\partial r}\right)^{2}+\left(\frac{\partial u_{z}}{\partial z}\right)^{2}\right] r d r d z-v \int_{D}\left[h\left(\frac{\partial v_{\theta}}{\partial r}-\frac{v_{\theta}}{r}\right)^{2}+\right. \\
\left.\quad+\left(\frac{d h}{d r}+\frac{2 h}{r}\right) v_{\theta} \frac{\partial v_{\theta}}{\partial r}+h\left(\frac{\partial v_{\theta}}{\partial z}\right)^{2}\right] r d r d z \quad\left(h=-\frac{2 \omega}{g}\right) \tag{4.10}
\end{gather*}
$$

In order for the right-hand side in (4.10) to be negative, and for flow (1.4) to be stable for any Reynolds number, it is suffictent that the functional

$$
\begin{equation*}
l(v)=\int_{r_{1}}^{r_{3}}\left[h\left(v^{\prime}-\frac{v}{r}\right)^{2}+\left(\frac{d h}{d r}+\frac{2 h}{r}\right) v v^{\prime}\right] r d r \tag{4.11}
\end{equation*}
$$

be nonnegative on the set of smooth functions $v(r)$ which vanish for $r=r_{1}, r_{2}$. Specifically, this requires that the function $h$ be nonnegative. But for Couette flow with allowance for (4.7) and (4.9) we find with a>o that

$$
h=-\frac{2 \omega}{g}=1+\frac{b}{a r^{2}} \geqslant 0, \quad l(v)=\int_{r_{1}}^{r_{2}} h\left(v^{\prime}-\frac{v}{r}\right)^{2} r d r>0 \quad\left(v^{\prime} \neq 0\right)
$$

[^0]We have just proved the stability of flow (1.3) in a linear approximation. liowever, according to the results of [12], nonlinear stability also follows.
5. Inetability, In this section we shall establish that under conditions (4.1) and (4.2) which ensure the appearance of secondary flows, principal flow (1.2) is unstable for sufficiently large Reynolds numbers.

In [13] this fact was established in the case of Couette flow through the asymptotic integration of system (5.1), (5.2) for $\lambda \rightarrow \infty$.

As we know, the matter is reduced to an investigation of the spectrum of the boundary value problem

$$
\begin{array}{cl}
\left(L-\alpha^{2}\right)^{2} u-\sigma\left(L-\alpha^{2}\right) u=2 \alpha^{2} \lambda \omega v, & \left(L-\alpha^{2}\right) v-\sigma v=-\lambda g u \\
u=u^{\prime}=0\left(r=r_{1}, r_{2}\right), & v=0\left(r=r_{1}, r_{2}\right) \tag{5.2}
\end{array}
$$

If all of the eigenvalues $\sigma_{k}(k=1,2, \ldots)$ for a given $\lambda$ have negative real parts, then flow (1.2) is stable. The existence of at least one eigenvalue with a positive real part results in instability. The applicability of the method to the nonlinear instability problem is justified in [12].

Theorem 5.1. Let conditions (4.1) and (4.2) be fulfilled. Then for any $\sigma>-\left(\alpha^{2}+\sigma_{0}\right)\left(\sigma_{0}>0\right.$ depends only on $r_{1}$ and $\left.r_{2}\right)$ there exists a sequence $\lambda_{1}<\lambda_{2}<\ldots ; \lambda_{n} \rightarrow \infty$ of $\lambda$ values such that problem (5:1), (5.2) has a nontrivial solution.

Proof. The differential operators in the left-hand sides of Equations (5.1) admit of the representation

$$
\begin{gather*}
\left(L-\alpha^{2}\right)^{2} u-\sigma\left(L-\alpha^{2}\right) u=\frac{1}{r} \operatorname{I\rho }_{0} \frac{d}{d r} \rho_{1} \frac{d}{d r} \rho_{2} \rho_{0 \sigma} \frac{d}{d r} \rho_{1 \sigma} \frac{d}{d r} \rho_{2 \sigma} u \\
\left(L-\alpha^{2}\right) v-\sigma v=\rho_{0 \sigma} \frac{d}{d r} \rho_{1 \sigma} \frac{d}{d r} \rho_{2 \sigma} v \tag{5.3}
\end{gather*}
$$

Where $\rho_{0}, \rho_{1}, \rho_{2}$ are functions defined in (3.1), and $\rho_{00}, \rho_{10}, \rho_{20}$ are given by Equations

$$
\begin{equation*}
r \rho_{0 \sigma}=\rho_{2 \sigma}=Y_{1}(r), \quad \rho_{1 \sigma}=\frac{r}{\rho_{2 \sigma}^{2}} \tag{5.4}
\end{equation*}
$$

where $\gamma_{1}(r)$ is some solution of Equation

$$
\begin{equation*}
\left(L-\alpha^{2}-\sigma\right) Y_{1}=0 \tag{5.5}
\end{equation*}
$$

If $\alpha^{2}+\sigma>-\sigma_{0}$, where $\sigma_{0}$ is the first eigenvalue of tire differential operator - $L$ for the second condition of (5.2), tnen Equation (5.5) has a solution $Y_{1}$ which is positive on the segment $\left[r_{1}, r_{2}\right]\left(1 f \alpha^{2}+0=8^{2}=0\right.$, as our $Y_{1}$ we simply take $I_{1}\left(\beta_{\mathrm{F}}\right)$ ).

By virtue of the results of Krein [3 and 4], (5.3) Amplies that the corresponding Green's operators $G_{10}, G_{20}$ are oscillatory. It remains for us to note that boundary value problem (5.1), (5.2) is equivalerit to the intecial equation

$$
\begin{equation*}
u=\mu B_{\eta} u, \quad B_{\sigma}=G_{2 \sigma} \omega G_{1 \jmath} g \tag{5.6}
\end{equation*}
$$

with the oscillatory operator $B_{0}$ and once again refer the reader to the results of [5]. The theorem has been proved.

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[^0]:    *) A slight alteration of this proof would enable us to show that stability also takes place when $\omega_{2} r_{2}^{2}-\omega_{1} r_{1}^{2}=0$.

